TOSSIM: Accurate and Scalable Simulation of Entire TinyOS Applications

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A Lesson from History

Simulation can provide

- The ability to inexpensively explore ideas
- A controlled environment
- Support for extensive observation
- Examples
 - SimOS
 - SimpleScalar
 - ns-2

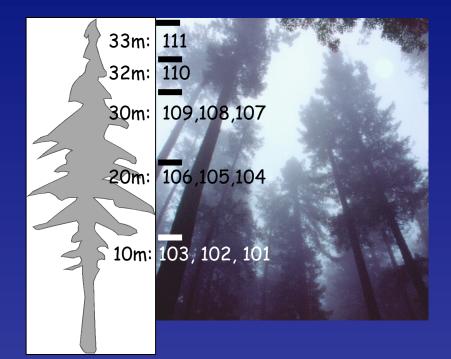
Accelerated research in their domains



Capturing the essential elements of their domains was critical to the utility of these simulators.

Mote Sensor Network Domain?

- Many tiny devices
- Embedment
- Non-deterministic
- Application-specific
- System interactions



What Do We Need to Capture?

Bridging

Implementations, not just algorithms

Completeness

- Spectrum of low-level protocols to applications
- Applications adapt to their environment
- Capture the cross-layer interactions
- Fidelity
 - Capture these interactions at a very fine grain
- Scalability
 - Examine behavior in dense or large networks

Our Approach: TOSSIM

- Simulator for TinyOS programs
- Compiles directly from TinyOS code
 - Executes code from many system layers
- Provides a flexible framework for adjusting fidelity
 - Based on TinyOS programming model
- Can scale to large numbers

Outline

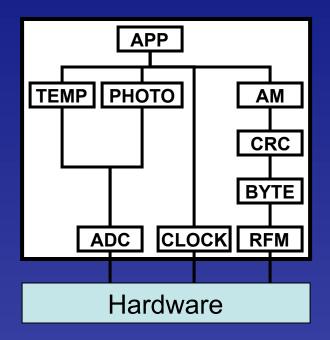
- Introduction
- TOSSIM architecture
- Evaluation
- Conclusion

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Standard TinyOS Program (what we start with)

Component Graph

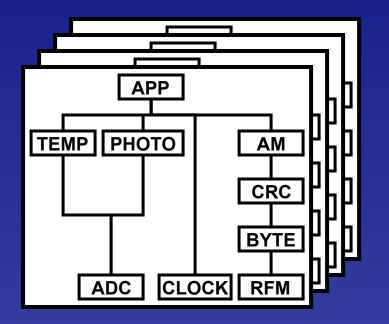


TOSSIM Adds Five Things

- Alternative compilation target
- Hardware component re-implementations
- Discrete event queue
- Radio and sensor models
- Communication services

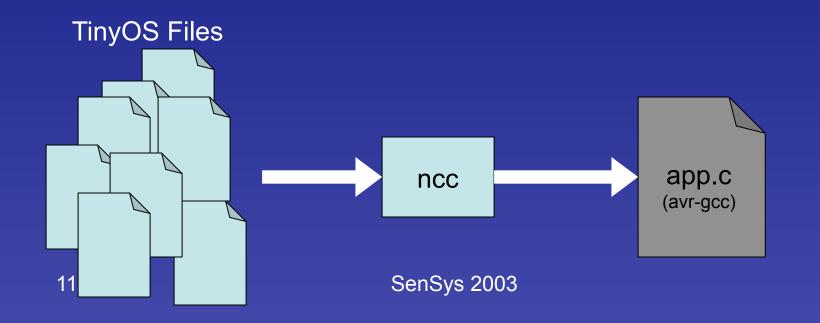
Multiple Component Graphs

Component Graphs



Compiler Support

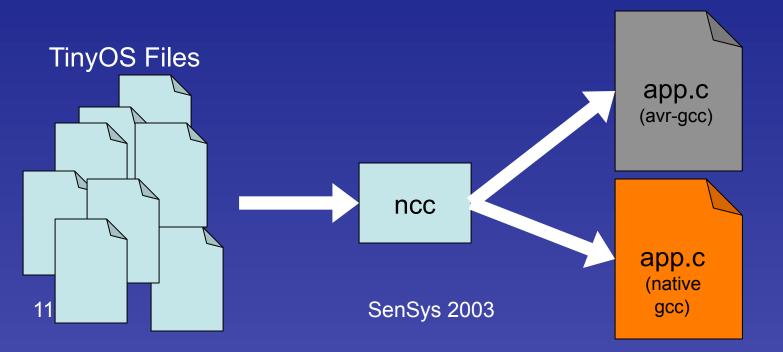
- "Simulator" target added to ncc compiler
- Rewrites all state declarations and accesses
 - Arrays of variables
 - Index into array based on current node



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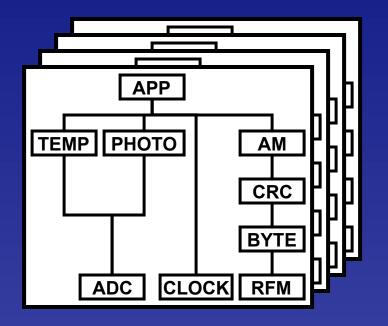
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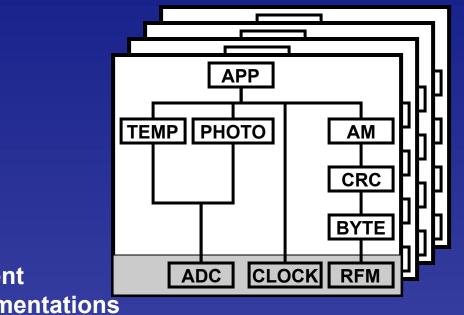
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Component Graphs

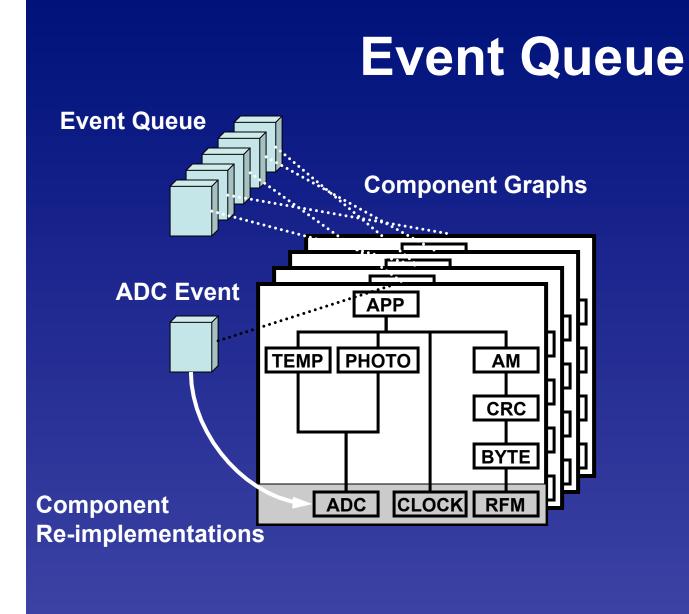


Component Re-implementations

Component Graphs



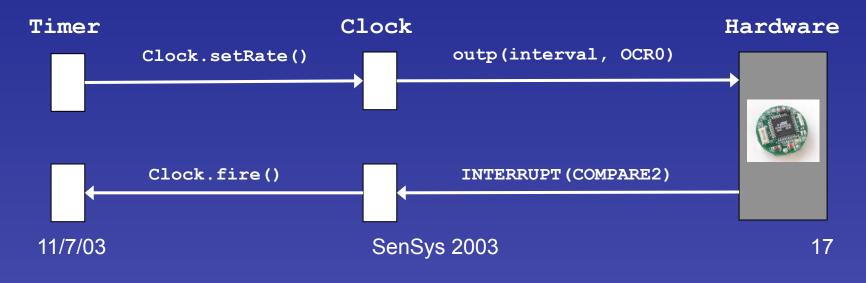
Component Re-implementations



Mapping TinyOS into TOSSIM

- TOSSIM events trigger TinyOS components

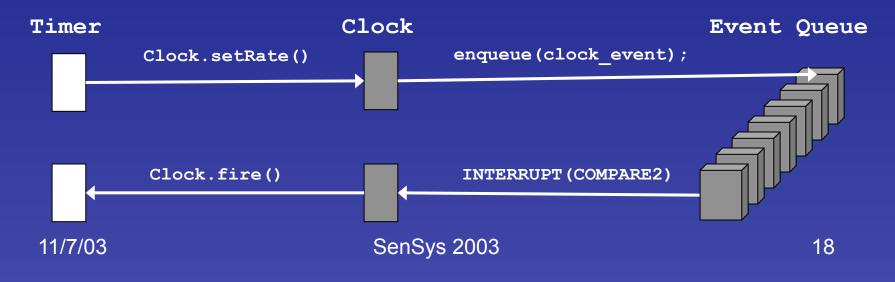
 Each event is for a specific mote and has a time
- TinyOS calls can enqueue TOSSIM events
- Hardware-level components re-implemented
 This boundary can change

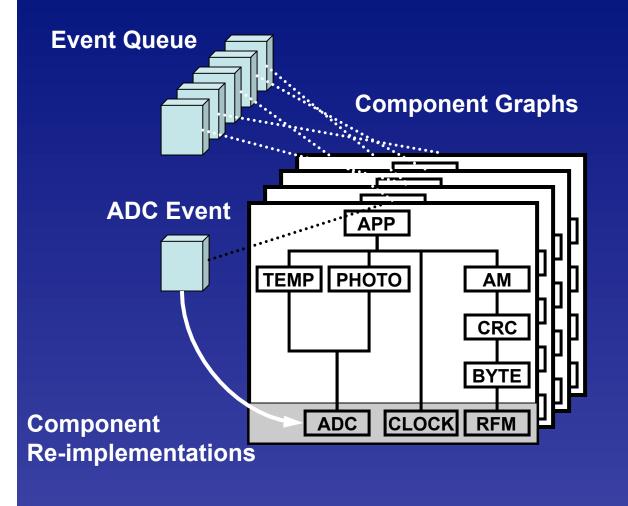


Mapping TinyOS into TOSSIM

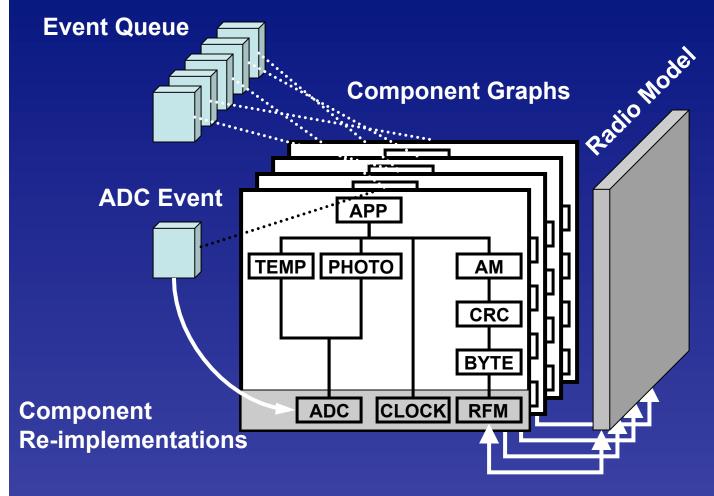
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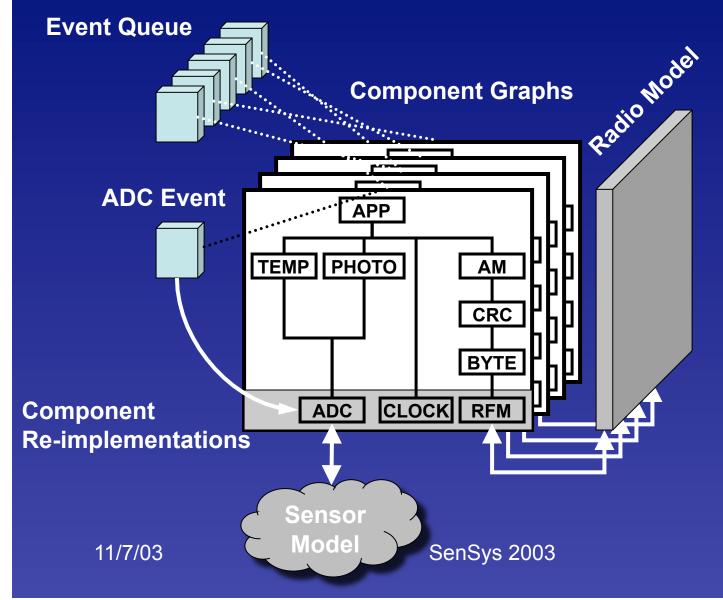




Radio Model

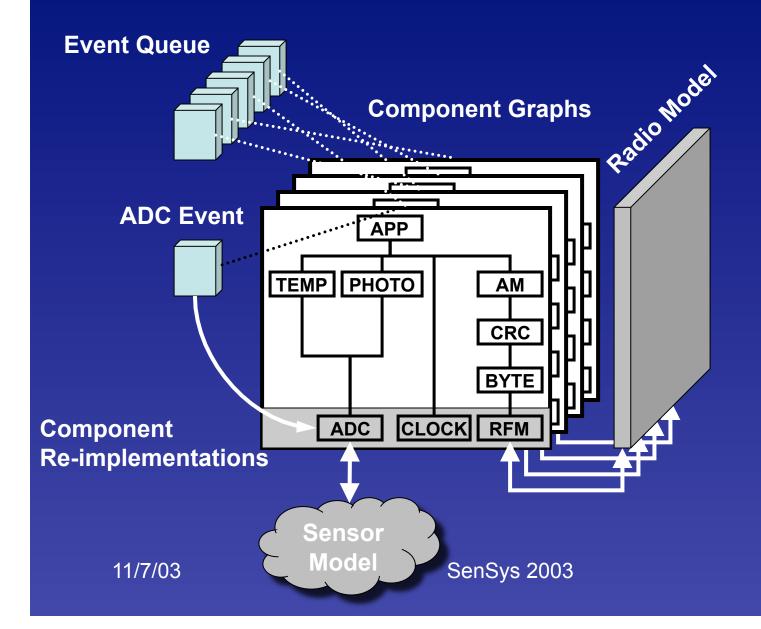


Sensor Model

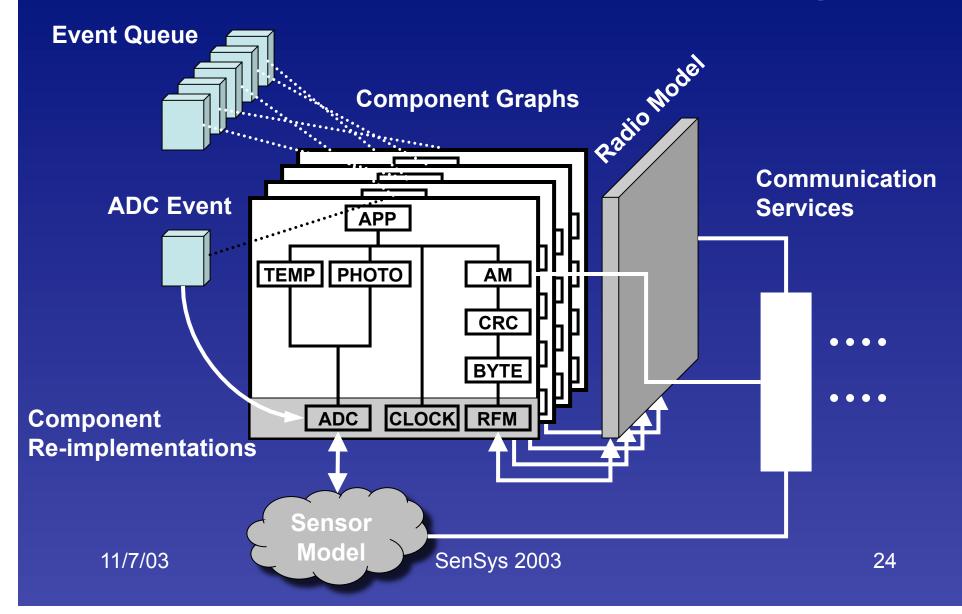


Radio Model

- Inter-node interaction
- Transmit and receive events
 - Who can hear whom graph
 - Receive radio state
 - Resolution function
 - Individual radio clocks (based on TinyOS code)
- Standard model: directed graph of bit error rates
 - Boil complex models to a connectivity graph
- Standard model: signal is the OR of transmissions
 - All transmissions have uniform strength
 - Hidden terminal problem



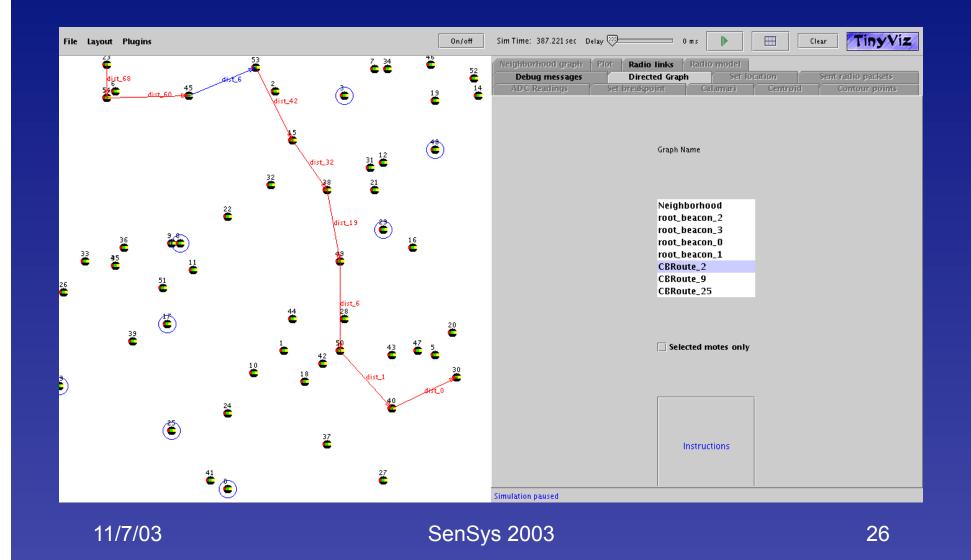
Actuation and Monitoring



Actuation and Monitoring

- Programs can actuate and monitor running simulations
 - Inject events, log messages
 - Change simulation state (loss rates, sensors)
- Keeps models external to TOSSIM
 - API to integrate models through sockets
 - TinyViz application

TinyViz



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What Do We Need to Capture? (revisited)

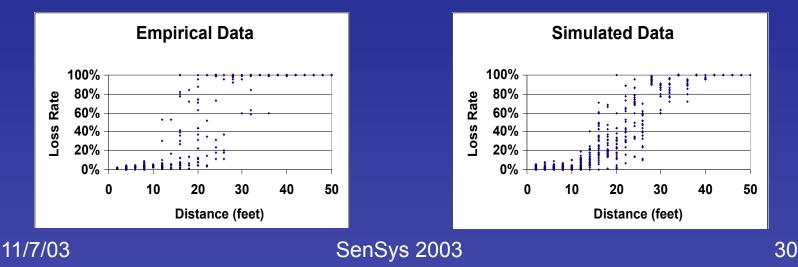
- Bridging
 - Implementations, not just algorithms
- Completeness
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Evaluation

- Bridging
 - Compiles directly from TinyOS code
- Fidelity
 - Mote networking
- Completeness
 - Complete applications
 - Unanticipated behavior
- Scalability
 - Tension between fidelity and scalability

Fidelity: Mote Networking

- Generated a loss model from empirical data
 Map empirical data to TOSSIM loss rates
- Start symbol failure, CRC checks, acknowledgement false negatives/positives
- Ran empirical experiment in TOSSIM



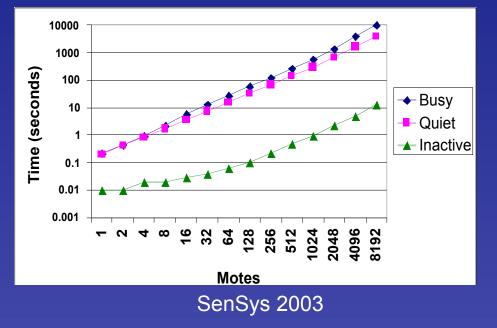
Completeness

- Network interactions
 - Hidden terminal problem, link asymmetry
 - Discovered bugs in the Surge application
- System-level race conditions
 - Network stack for mica: ChannelMonM start symbol detection and packet transmission
- Testing at low levels
 - State machine rene stack implementation
- Application-level logic driving simulation

 Maté, TinyDB

Scalability

- 10 virtual seconds
- Scales to thousands of nodes
- ~30 network active nodes in real time
 - 40,000 radio events per second for each mote



11/7/03

Scalability Continued

- 30 nodes * 40,000 events = 1.2 million TOSSIM events/second
- Bit-level simulation is the bottleneck
 - But we can move the re-implementation line…

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Some Cautionary Notes

- Non-preemptive execution
 - Handlers execute instantaneously
- Signal strength
 - Results and assumptions
- Independent bit errors
- Perfect channel sense
- TOSSIM has not been validated
 - A basis for comparison, but not the basis

Extensions (help appreciated!)

- Changing the re-implementation boundary
 - Packet level simulation
 - Talking to real motes
- Heterogeneous networks
 - Additional compiler support
 - Compelling applications?
- Power modeling
 - Source annotation for CPU timing
 - Component power state transitions



Concluding Thoughts

- Event-driven OS maps to event-driven simulation
- TOSSIM as a TinyOS development environment
 - Validate with deployment
- Simulate at the lowest level
 - More than what you think you need
 - Capture the *unanticipated* problems
- Capture the mess, but not reality
 - Model the observed behavior, not the phenomena that cause that behavior
 - Do we understand these systems well enough yet?

Questions



Backup Slides



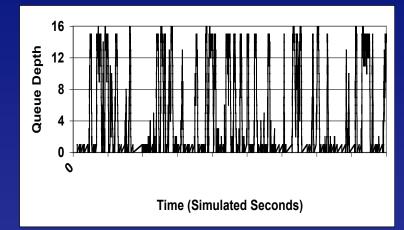
Why Not ns-2?

- Not designed for application interaction
- Algorithms, not implementations
- Need a TinyOS simulator, not just the network

Surge

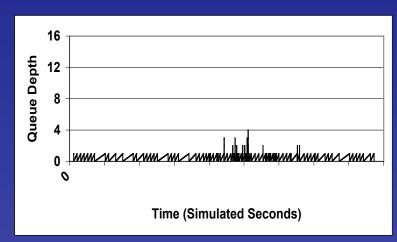
- Empirically, Surge protocol showed poor performance
 - Users added TinyDB attribute to monitor protocol
 - Everything looked fine
- Tested Surge application in TOSSIM
 - Observed traffic surges
 - Send queue overflow
- TOSSIM revealed the problem
 - Cycles + acks + retransmission policy
 - Lose TinyDB query results indicating the problem

Surge, Continued



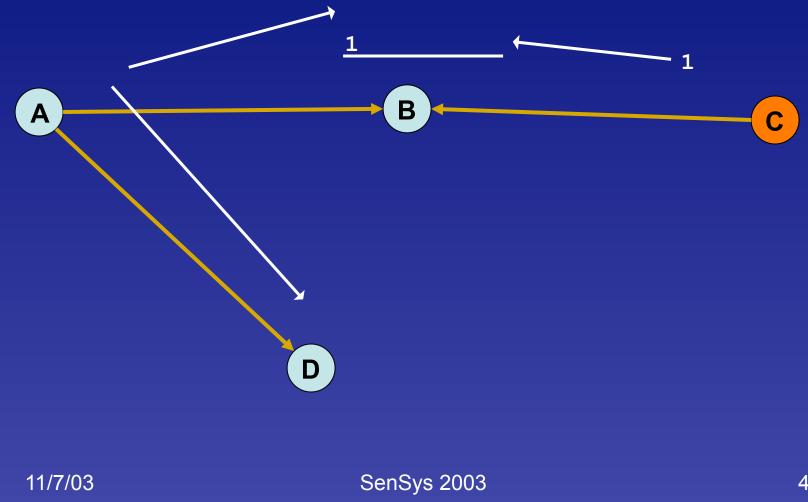
Observed Behavior

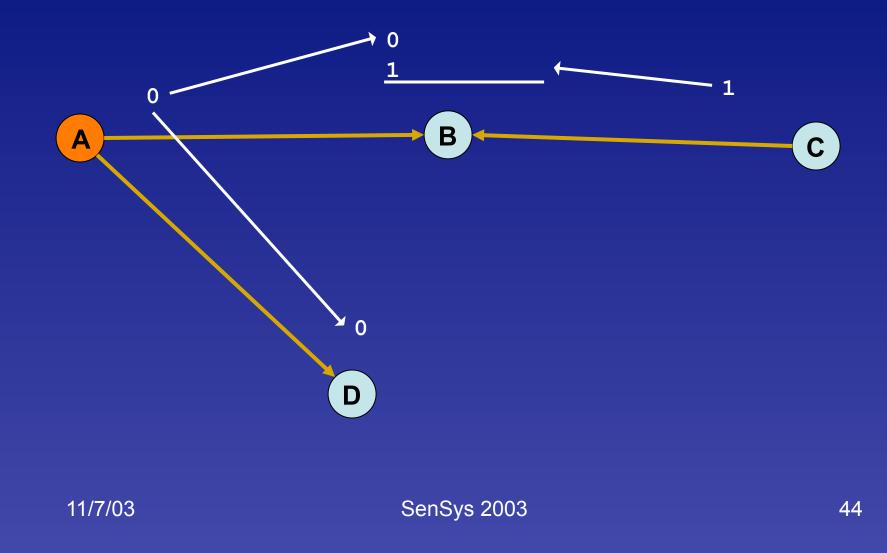
Fixed Algorithm

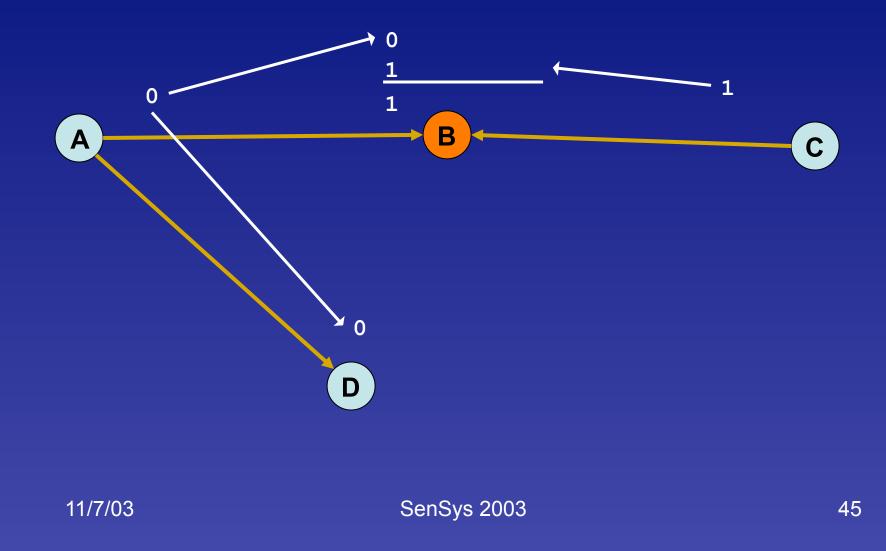


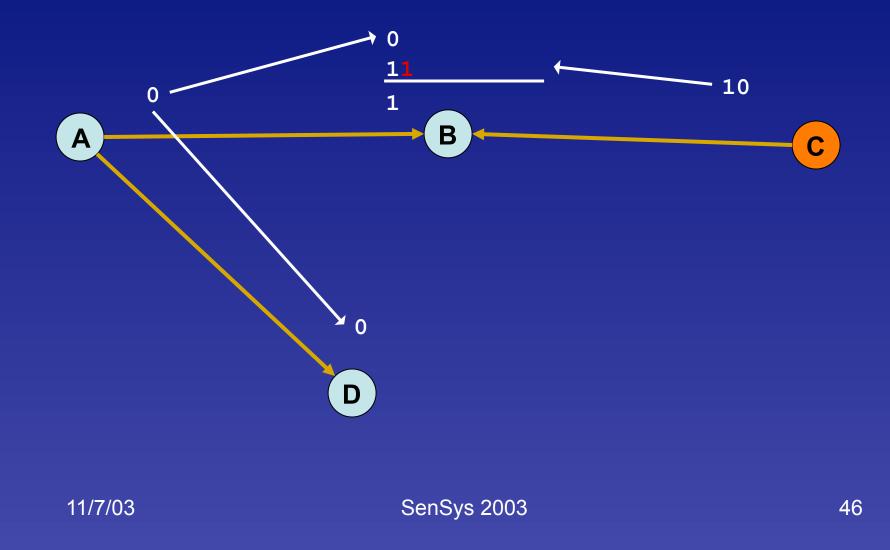
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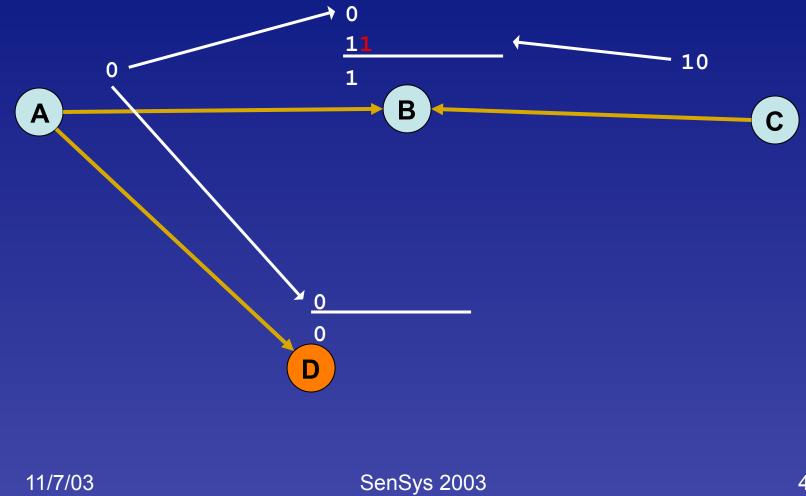
SenSys 2003











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